

# Domain decomposition techniques for hyperbolic equations on unstructured grids

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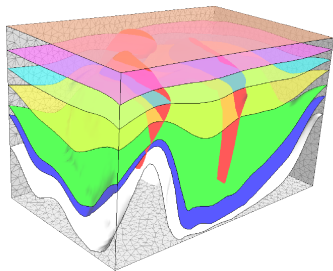
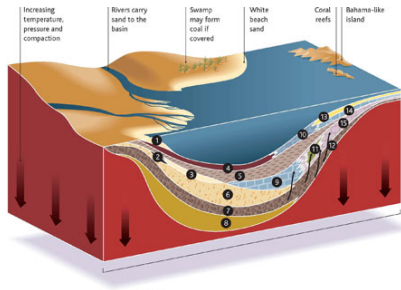
MOX, Politecnico di Milano

June 5th, 2012

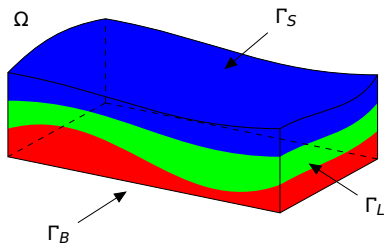


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# Motivation - sedimentary basins



# Mathematical model



$$\left\{ \begin{array}{ll} \nabla \cdot (\mu(\nabla \mathbf{u} + \nabla \mathbf{u}^T)) - \nabla p = -\rho \mathbf{g} & \text{in } \Omega \times (0, T] \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \times (0, T] \\ \frac{\partial}{\partial t} \{\rho, \mu\} + \mathbf{u} \cdot \nabla \{\rho, \mu\} = 0 & \text{in } \Omega \times (0, T] \\ \rho = \rho_0, \quad \mu = \mu_0 & \text{in } \Omega \times \{0\} \\ \mathbf{u} = \bar{\mathbf{u}} & \text{on } \Gamma \end{array} \right.$$

# Stokes system discretization - 1

bilinear forms

$$a(\mathbf{u}, \mathbf{v}) = \int_{\Omega} \mu \nabla \mathbf{u} : \nabla \mathbf{v} \quad \forall \mathbf{u}, \mathbf{v} \in \mathbf{H}^1$$

$$b(p, \mathbf{v}) = \int_{\Omega} p \nabla \cdot \mathbf{v} \quad \forall p \in L_0^2, \quad \forall \mathbf{v} \in \mathbf{H}^1$$

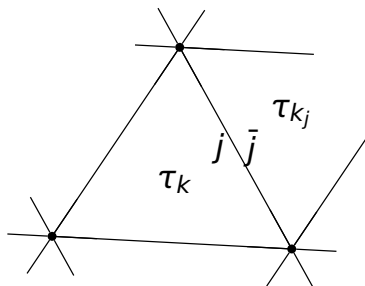
$$f(\mathbf{v}) = - \int_{\Omega} \rho \mathbf{g} \cdot \mathbf{v} \quad \forall \mathbf{v} \in \mathbf{H}^1$$

weak formulation

$$\begin{cases} a(\mathbf{u}, \mathbf{v}) + b(p, \mathbf{v}) = f(\mathbf{v}) & \forall \mathbf{v} \in \mathbf{X} \\ b(q, \mathbf{u}) = 0 & \forall q \in S \end{cases}$$

## Stokes system discretization - 2

- tetrahedral grid  $\mathcal{T}_h(\Omega)$ ,  $n_e$  elements and  $n_p$  points
- element  $\tau_k$ ,  $\bigcup_k \tau_k = \mathcal{T}_h$
- $X = \{v_h \in H^1 : v_h|_{\tau_k} \in \mathbb{P}_b^1\}$
- $S = \{q_h \in L_0^2 : q_h|_{\tau_k} \in \mathbb{P}^1\}$



# Characteristic function

$$\lambda_i(\mathbf{x}) = \begin{cases} 1 & \text{if } \mathbf{x} \in \Omega_i \\ 0 & \text{if } \mathbf{x} \notin \Omega_i \end{cases}$$

$i = \text{red}, \text{green}, \text{blue}$  (s components)

$$\rho = \sum_{i=1}^s \lambda_i \rho_i, \quad \mu = \sum_{i=1}^s \lambda_i \mu_i$$

evolution equation for  $\lambda$

$$\frac{\partial \lambda}{\partial t} + \mathbf{u}^n \cdot \nabla \lambda = 0$$

# Characteristic function discretization - 1

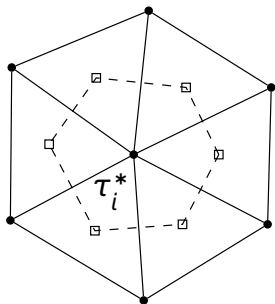
- multi-fluid support
- robust
- efficient
- automatic topology changes

## Characteristic function discretization - 2

- finite volume explicit method

$$\boldsymbol{\lambda}_h^{n+1} = \boldsymbol{\lambda}_h^n - \Delta t^n \mathbf{u}^n \cdot \nabla \boldsymbol{\lambda}_h^n$$

- dual mesh  $\mathcal{T}_h^*(\Omega)$  with  $n_p$  elements
- element  $\tau_i^*$ ,  $\bigcup_i \tau_i = \mathcal{T}_h^*$
- $\lambda_h \in V_0^*$ ,  $V_0^* = \{\varphi_h \in L^2 : \varphi_h|_{\tau_i^*} \in \mathbb{P}^0\}$
- $\phi_h \in V_1$ ,  $V_1 = \{\varphi_h \in C^1 : \varphi_h|_{\tau_k} \in \mathbb{P}^1\}$
- $\phi_h^n = \mathbf{I}_h^1 \lambda_h^n$  ( $\phi_i^n \equiv \lambda_i^n$ )





# Flux approximation

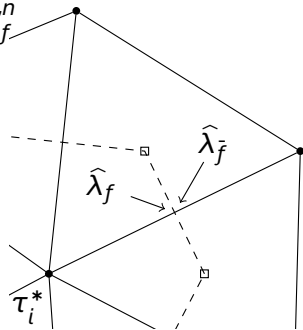
finite volume approximation on the dual grid

$$\lambda_s^{n+1} = (1 + D^n) \lambda_s^n - \sum_f \nu_f^n \Phi(\hat{\lambda}_{s,f}^n, \hat{\lambda}_{s,\bar{f}}^n)$$

$$D^n = \frac{\Delta t^n}{|\tau|} \oint_{\partial\tau} \mathbf{u} \cdot \mathbf{n} = \sum_f \nu_f^n$$

$$\nu_f^n = \frac{\Delta t^n}{|\tau|} \int_f \mathbf{u} \cdot \mathbf{n}$$

$$\hat{\lambda}_{s,f}^n = \lambda_s^n + \delta \lambda_{s,f}^n$$



# Interface values - 1

$\delta\lambda_{s,f}^n$  comes from the constrained minimization problem

$$\left\{ \begin{array}{l} \min_{\delta\lambda_{s,f}^n} \frac{1}{2} \sum_s \left( \lambda_s^n - \phi_{s,f}^n + \delta\lambda_{s,f}^n \right)^2 \\ \sum_s \delta\lambda_{s,f}^n = 0 \\ -\lambda_s^n < \delta\lambda_{s,f}^n < \min \left( \frac{1+D^n - \nu_f^n |f|}{\nu_f^n |f|}, 1 - \lambda_s^n \right) \end{array} \right.$$

$\delta\lambda_{s,f}^n$  as a best fit approx of LS <sup>1</sup>

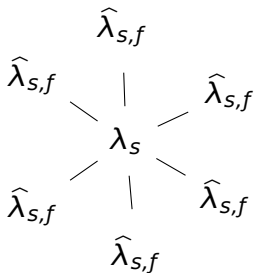
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<sup>1</sup>Villa A., Formaggia L. Implicit tracking for multi-fluid simulations. JCP 229 (2010) 5788–5802

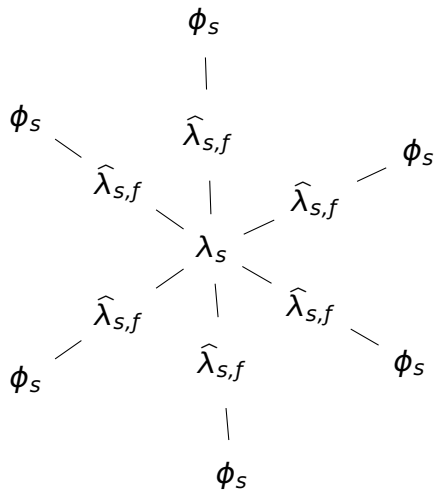
# Interface values - 2

$\lambda_s$

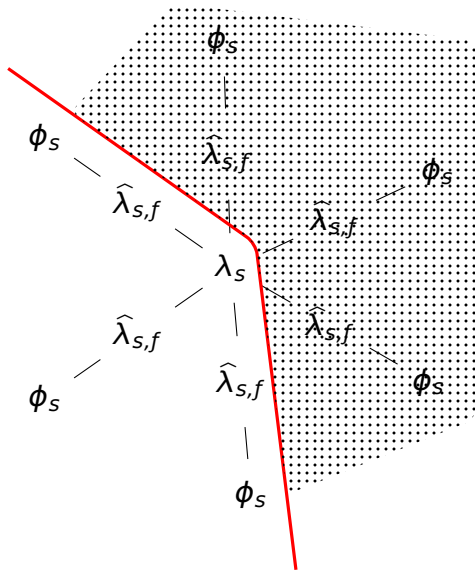
## Interface values - 2



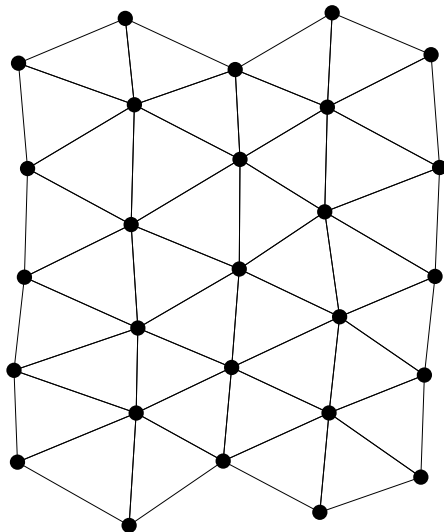
## Interface values - 2



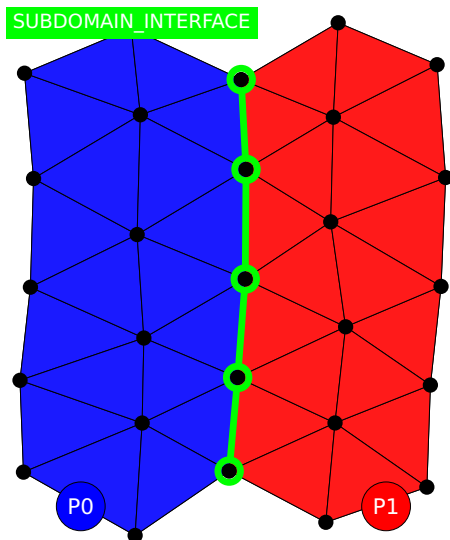
## Interface values - 2



# Domain decomposition with hyperbolic eqns

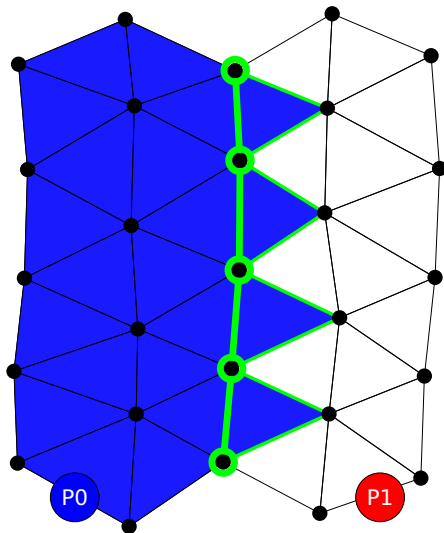


# Domain decomposition with hyperbolic eqns

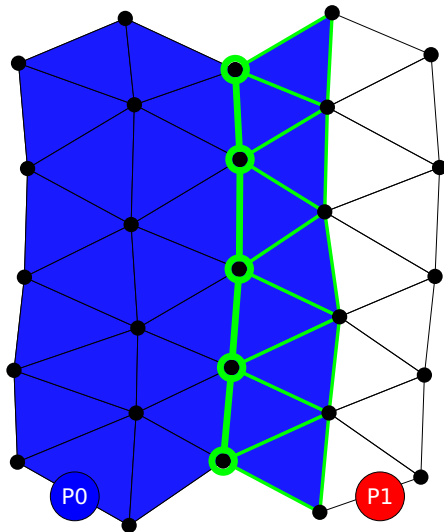




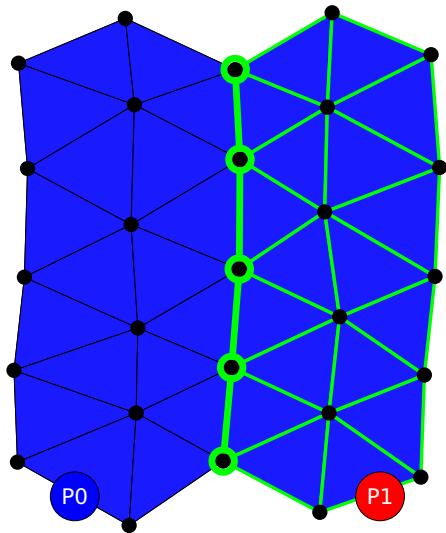
# Domain decomposition with hyperbolic eqns



# Domain decomposition with hyperbolic eqns



# Domain decomposition with hyperbolic eqns



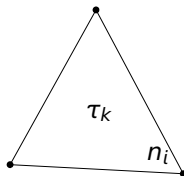
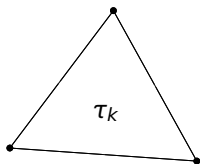
- finite element library
- originally developed for life sciences
- advanced FSI solvers
- heart modeling
- 1D models
- multiscale
- parallel
- based on Trilinos

## the MapEpetra object

- stores 2 Epetra\_MapS
  - Unique: objects used to assembly
  - Repeated: objects used to share information
- handles import/exports between different maps
- operator=()
- operator+=()
- operator|=() for block support
- used to build all algebraic objects

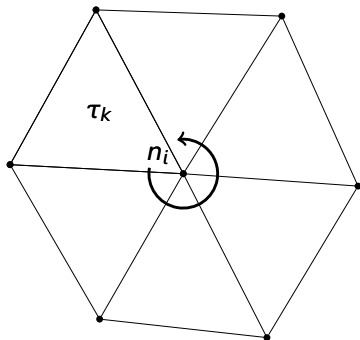
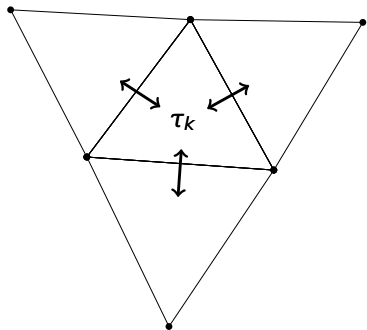
# Overlapping maps - 1

- based on connectivity
- each geometric entity knows its neighborhood



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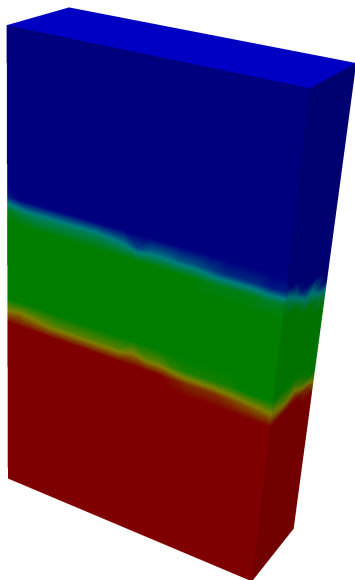
# Overlapping maps - 2

## Algorithm

- build neighborhood information on the full mesh
- partition the mesh
- delete full mesh
- identify subdomain interface entities  
(check on neighbors)
- init searching set with subdomain interface entities
- for: level of overlap
  - add all neighbors not on current partition
  - replace searching set with added entities

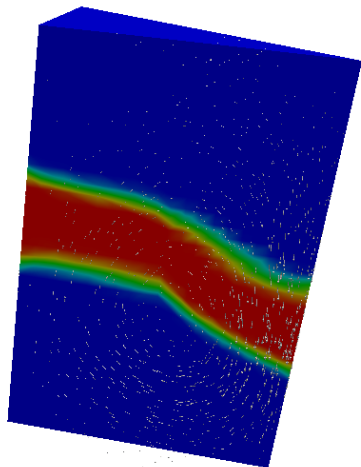
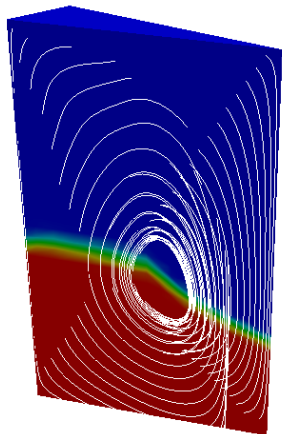


# Simulation setup

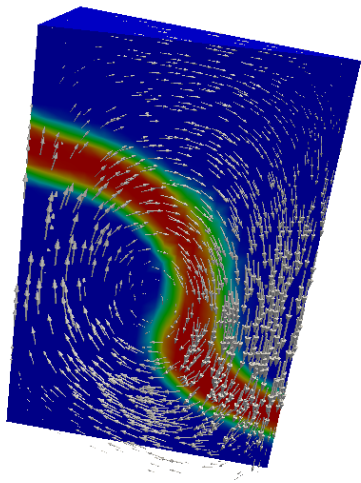
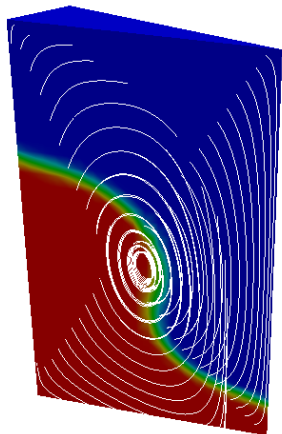


- $n_e \sim 200K$
- $n_p \sim 40K$
- dof  $\sim 750K$
- $\mu = 3.0, \rho = 3.5$
- $\mu = 2.0, \rho = 0.2$
- $\mu = 0.1, \rho = 1$

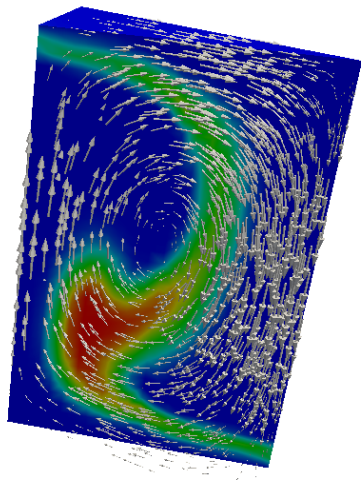
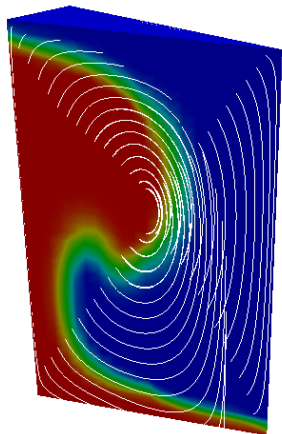
# Time evolution



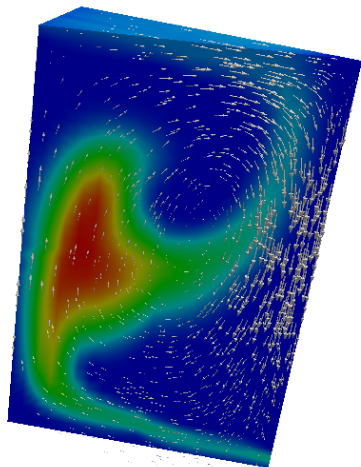
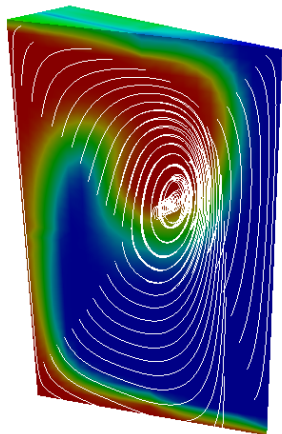
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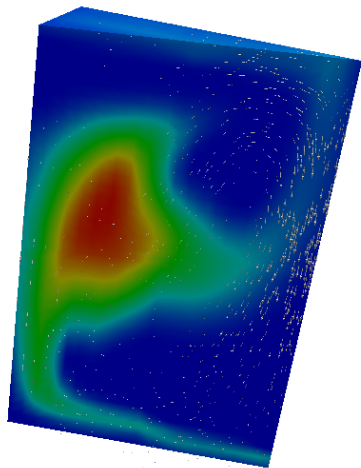
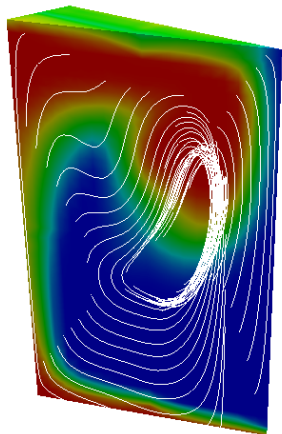
# Time evolution



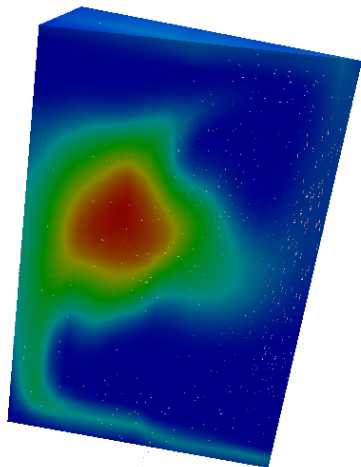
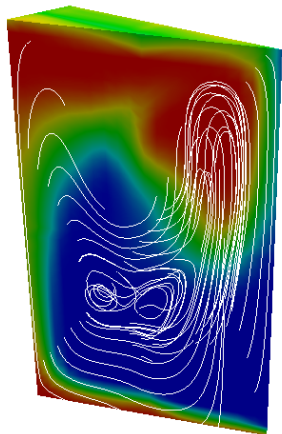
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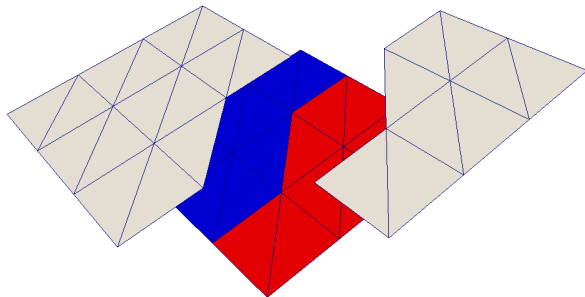
# Performance analysis

- $\mu_1/\mu_2 \sim 1 \rightarrow CN = 7 \cdot 10^5$
- $\mu_1/\mu_2 \sim 10 \rightarrow CN = 2.5 \cdot 10^6$
- $\mu_1/\mu_2 \sim 100 \rightarrow CN = 2.5 \cdot 10^7$
- preconditioning computation
  - reuse?
  - Vanka smoothers
  - HYPRE
- mesh memory footprint

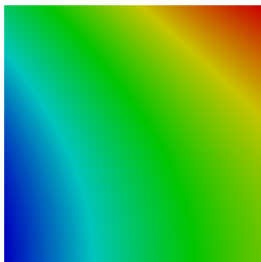


# Assembly

- physically replicated mesh
- resort to overlapping maps to avoid comm?
- computation intensive vs memory/comm intensive
- create graph for matrix init
- virtual subdomain interface nodes



# ADR test



- 4.5M elements
- 2.2M points
- 4K interface elements
- 4K interface points

# Performance

| PROC/NODE | STANDARD | REPEATED | GAIN  |
|-----------|----------|----------|-------|
| 2/2       | 11.52    | 11.1     | 3.6%  |
| 4/4       | 6.13     | 5.89     | 3.9%  |
| 8/8       | 3.11     | 3.01     | 3.2%  |
| 16/2      | 1.71     | 1.64     | 4.1%  |
| 16/4      | 1.63     | 1.62     | 0.0%  |
| 16/16     | 1.80     | 1.71     | 5.0%  |
| 64/8      | 0.47     | 0.42     | 10.6% |
| 64/64     | 0.21     | 0.18     | 14.3% |

thanks for the attention... go watch the poster!

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## LifeV::Geophysics@EuroTUG2012

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